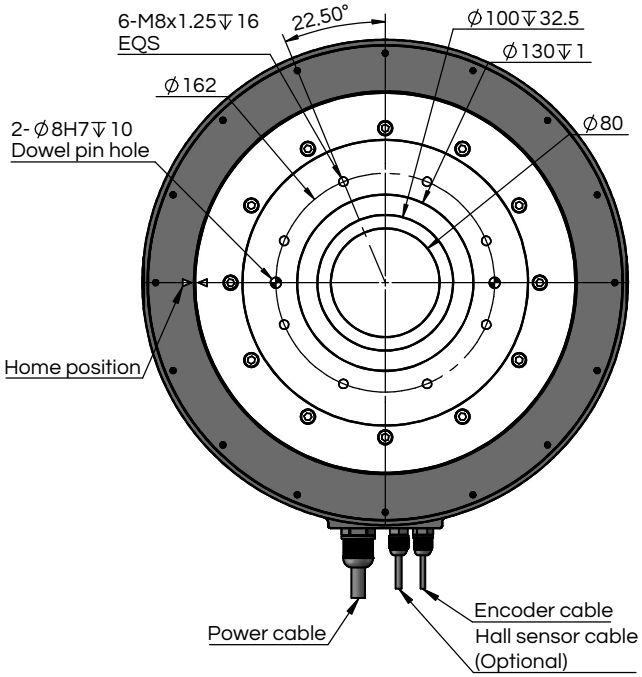
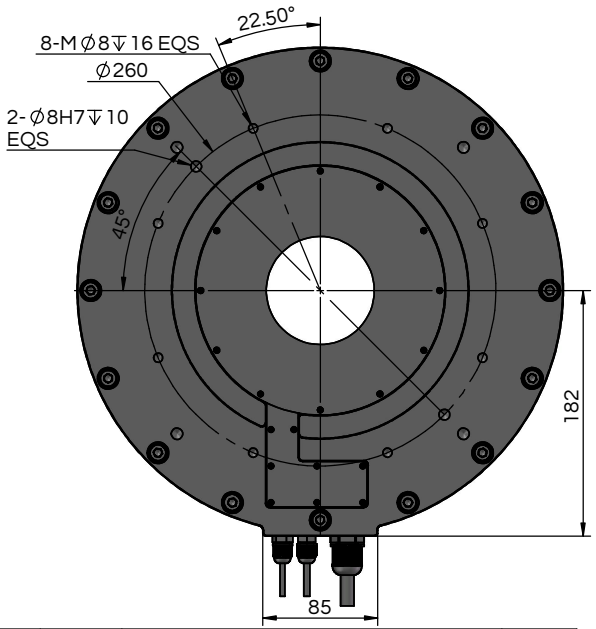
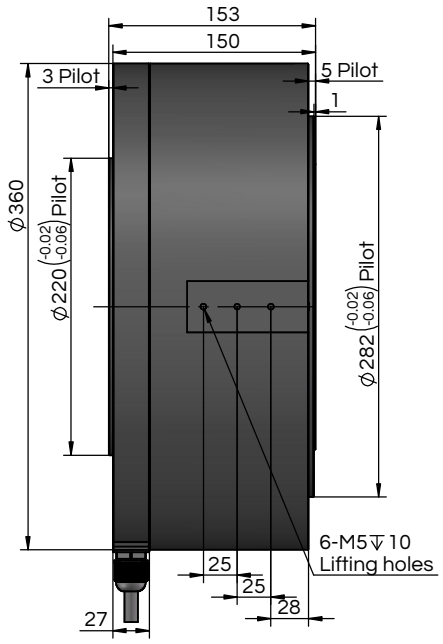






No.	Specification	Unit	Value
1	Flange-type	-	-
2	Continuous Torque	Nm	264
3	Peak Torque	Nm	721
4	Rated Speed	Rpm	150
5	Maximum Speed	Rpm	200
6	Continuous Current	Arms	15
7	Peak Current	Arms	45
8	Torque Constant	Nm/Arms	17.6
9	Back EMF Constant*	Vrms/rad/s	11.4
10	Resistance Phase to Phase at 25°C	Ω	1.65
11	Inductance Phase to Phase at 25°C	mH	8.9
12	Number of poles	-	40
13	Rotor Inertia	$kg{\cdot}m^2$	0.24
14	Incremental encoder resolution	ppr	4350000
15	Absolute encoder resolution	ppr	24 bit (16777216)
16	Absolute Position Accuracy	arcsec	±15
17	Repeat Position Accuracy	arcsec	±2
18	Axial Load	N	30000
19	Radial Load	Nm	360
20	Axial Run Out*2	um	5(optional)
21	Radial Run Out*3	um	5(optional)
22	Mass	kg	63
23	IP level	-	40
24	Motor Color	-	black
25	Max. DC BUS	V	220

*1 The back electromotive force (back EMF) is the value measured between any two conductors when the motor is running at a constant speed.
*2 *3 Please contact sales.

NOTE:
1.Please make sure the flatness of customer's surface when mounting the motor must be within 0.01/300 mm.
2.The mounting surface without black oxidation.

Wiring Definition	Installation Instructions	Maintenance Instructions

ITEM	DATE	MODIFIED	DESCRIPTION	APPD

TKOOLLE MOTION CONTROL

SCALE	UNIT		Model	TDI-360150		
1:X	mm		Desc	Rotary Motor		
GENERAL TOLERANCE			Surface	Black oxidation	DRN	Tang
Up to 6 / 6 to 30 / 30 to 120 / 120 to 300 / 300 to 600			DWG.NO	M360A110	CHK	Zhou
±0.1	±0.2	±0.3 ±0.4 ±0.5	Sheet	1-1	APPD	Le

TKOOLLE MOTION CONTROL INTERNATIONAL CO.,LIMITED DATE 17-Jul-25